

Tire Gripper

Type R106



Characteristics:

parallel finger movement

actuator pneumatic or electric

position checks through proximity switches (optional)

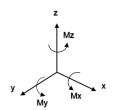
optionally with object retention upon loss of air pressure

materials: stainless steel, fingers made from anodized aluminum

high torques in all three dimensions

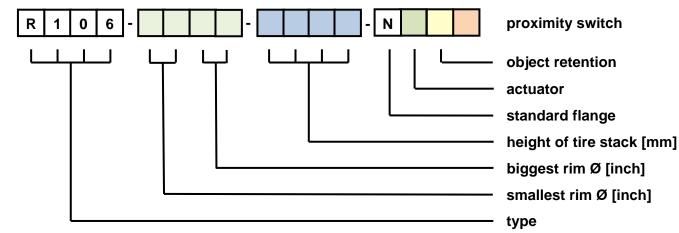
long stroke with end-of-stroke damping on both sides

inside and outside gripping applications with arbitrary geometry and number of fingers



Technical data:	
type:	R106
temperature:	-30 bis +80 °C
mass (by geometry):	approx. 20-50 kg
load capacity Fz	approx. 10.000 N

Order Number:



actuator	
kind	sign
pneumatic	Р
electric	E

object retention	
kind	sign
object retention fingers opening	Α
without object retention	0

proximity switch		
sensor	sign	
with	۱۸/	
proximity swith	W	
without	0	
proximity swith	0	

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